

### Memory FeRAM

# 16 K (2 K × 8) Bit Dual SPI

# MB85RD16LX

#### **■ DESCRIPTION**

MB85RD16LX is a FeRAM (Ferroelectric Random Access Memory) chip in a configuration of 2,048 words × 8 bits, using the ferroelectric process and silicon gate CMOS process technologies for forming the nonvolatile memory cells.

MB85RD16LX can be accessed via Serial Peripheral interface (SPI) or Dual SPI.

The MB85RD16LX is able to retain data without using a back-up battery, as is needed for SRAM.

The memory cells used in the MB85RD16LX can be used for  $10^{13}$  read/write operations, which is a significant improvement over the number of read and write operations supported by Flash memory and  $E^2$ PROM.

The MB85RD16LX does not take long time to write data like Flash memory or E<sup>2</sup>PROM, and MB85RD16LX takes no wait time.

#### **■ FEATURES**

• Non-volatile memory configuration : 2,048 words × 8 bits

• Interface : SPI (Serial Peripheral Interface) / Dual SPI

Corresponding to SPI mode 0 (0, 0) and mode 3 (1, 1)

• Operating frequency : 15 MHz (Max for SPI) / 7.5 MHz (Max for Dual SPI)

• High endurance : 10<sup>13</sup> times / byte

• Data retention : 27.3 years (+105°C)

8.4 years (+125°C)

Operating power supply voltage : 1.65 V to 1.95 V

Low power consumption : Operating power supply current 0.7 mA (Max@15 MHz)

Standby current 11  $\mu$ A (Max@+125°C), 1  $\mu$ A (+25°C)

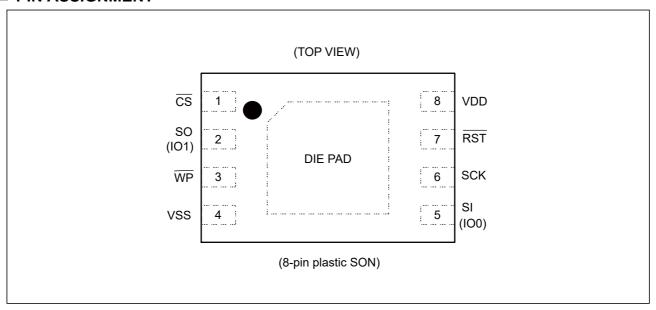
• Operation ambient temperature : −40°C to +125°C

Package : 8-pin plastic SON

RoHS compliant

Fujitsu Semiconductor Memory Solutions Limited has changed its name to RAMXEED Limited. RAMXEED Limited will continue to offer and support existing products while maintaining Fujitsu's part number unchanged.

#### **■ PIN ASSIGNMENT**

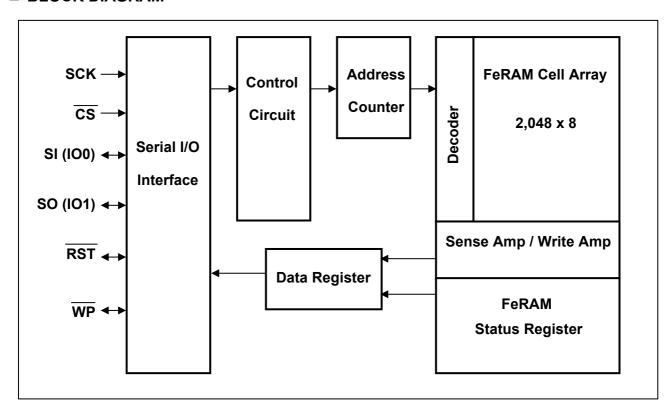


#### ■ PIN FUNCTIONAL DESCRIPTIONS

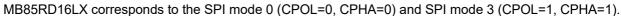
Pin No.	Pin Name	Functional description
1	CS	Chip Select pin This is an input pin to activate the device. When $\overline{CS}$ is the "H" level, device is in deselect (standby) status and SO/SI become High-Z. Inputs from other pins are ignored at this time. When $\overline{CS}$ is the "L" level, device is in select (active) status. $\overline{CS}$ has to be the "L" level before inputting op-code.
3	WP	Write Protect pin This is an input pin to control writing to a status register. The writing of status register (see "■ STATUS REGISTER") is protected in relation with WP and WPEN bit of the status register. See "■WRITING PROTECT" for detail.
7	RST	Reset pin This is an input pin to reset the device internally. When RST is the "L" level, the interface is inactive and the SPI state machine is reset. RST pin need to be "L" at power on.
6	SCK	Serial Clock pin This is a clock input pin to input/output serial data. Inputs are latched synchronously to the rising edge, Outputs occur synchronously to the falling edge.
5	SI (IO0)	Serial Data Input pin (Serial Data Input Output 0) This inputs op-code, addresses or writing data and outputs reading data. This is High-Z during standby.
2	SO (IO1)	Serial Data Output pin (Serial Data Input Output 1) This outputs reading data or status register and inputs addresses or writing data. This is High-Z during standby.
8	VDD	Supply Voltage pin
4	VSS	Ground pin
DIE PAD	-	It is allowed for the DIE PAD on the bottom of the SON8 package to be floating (no connection to anything) or to be connected to VSS.

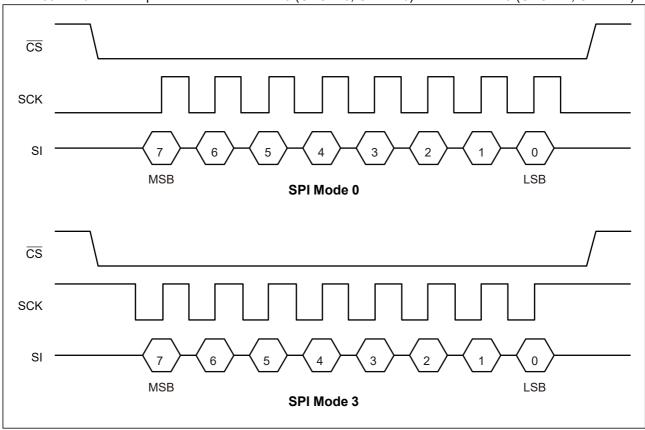
<sup>(\*)</sup>When using Dual SPI instructions, the SI and SO pins become bidirectional IO0 and IO1 pins.

#### **■ BLOCK DIAGRAM**



#### ■ SPI MODE





#### ■ SERIAL PERIPHERAL INTERFACE (SPI)

#### · Standard SPI

MB85RD16LX works as a slave of SPI. Standard SPI uses the SI serial input pin to write op-code, addresses or data to the device on the rising edge of SCK. The SO serial output pin is used to read data or status register from the device on the falling edge of SCK.

#### · Dual SPI

MB85RD16LX supports Dual SPI mode using the "Read Dual I/O (RDIO, B3h)" and "Write Dual I/O (WDIO, B2h)" op-code. When using Dual SPI op-code, the SI and SO pins become bidirectional IO0 and IO1 pins.

### **■ STATUS REGISTER**

Bit No.	Bit Name	Function
7	WPEN	Status Register Write Protect This is a bit composed of nonvolatile memories (FeRAM). WPEN protects writing to a status register (see "■ WRITING PROTECT") relating with WP input. Writing with the WRSR command and reading with the RDSR command are possible.
6 to 4	_	Not Used Bits These are bits composed of nonvolatile memories, writing with the WRSR command is possible. These bits are not used but they are read with the RDSR command.
3	BP1	Block Protect This is a bit composed of nonvolatile memory. This defines size of write protect block for the WRITE command and WDIO command (see "■ BLOCK
2	BP0	PROTECT"). Writing with the WRSR command and reading with the RDSR command are possible.
1	WEL	Write Enable Latch This indicates FeRAM Array and status register are writable. The WREN command is for setting, and the WRDI command is for resetting. With the RDSR command, reading is possible but writing is not possible with the WRSR command. WEL is reset after the following operations.  After power ON.  After WRDI command recognition.  At the rising edge of CS after WRSR command recognition.  At the rising edge of CS after WRITE command recognition.  At the rising edge of CS after WDIO command recognition.
0	0	This is a bit fixed to "0".

#### ■ OP-CODE

MB85RD16LX accepts 7 kinds of conventional command (WREN to RDID) and 2 kinds of enhanced command (RDIO to WDIO) specified in op-code. Op-code is a code composed of 8 bits shown in the table below. Do not input invalid codes other than those codes. If  $\overline{\text{CS}}$  is risen while inputting op-code, the command is not performed.

Name	Description	Op-code
WREN	Set Write Enable Latch	0000 0110в
WRDI	Reset Write Enable Latch	0000 0100в
RDSR	Read Status Register	0000 0101в
WRSR	Write Status Register	0000 0001в
READ	Read Memory Code	0000 0011в
WRITE	Write Memory Code	0000 0010в
RDID	Read Device ID	1001 1111в
RDIO	Read Dual I/O	1011 0011в
WDIO	Write Dual I/O	1011 0010в

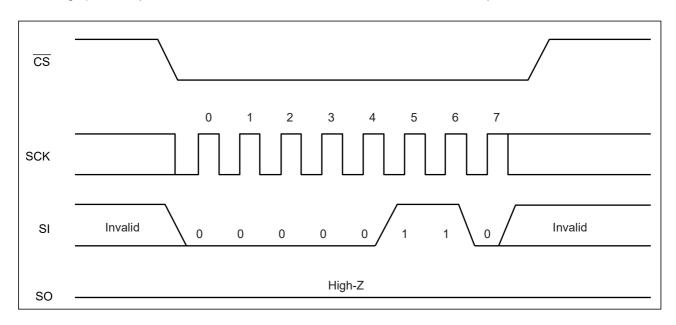
#### Notes

- 1-1. Standard SPI Input Address (2bytes) SI = X, X, X, X, X, A10, A9, A8, A7, A6, A5, A4, A3, A2, A1, A0 (Upper 5bit = any)
- 1-2. Dual SPI Input Address (2bytes) IO0 = X, X, A9, A7, A5, A3, A1, X IO1 = X, X, A10, A8, A6, A4, A2, A0 (Upper 4bit and lower 1bit = any)
- 2-1. Standard SPI I/O Data SI (or SO) = (D7, D6, D5, D4, D3, D2, D1, D0)
- 2-2. Dual SPI I/O Data IO0 = (D6, D4, D2, D0) IO1 = (D7, D5, D3, D1)

#### **■ COMMAND**

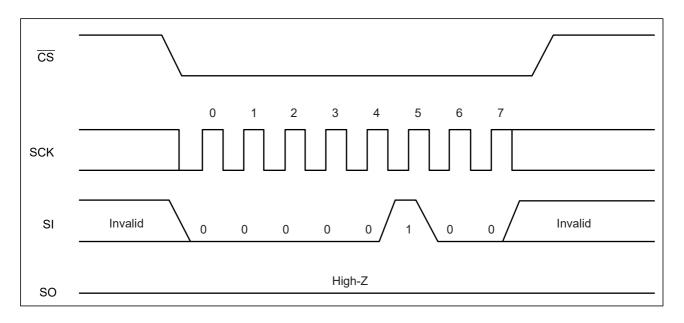
#### WREN

The WREN command sets WEL (Write Enable Latch). WEL shall be set with the WREN command before writing operation (WRSR command, WRITE command and WDIO command).



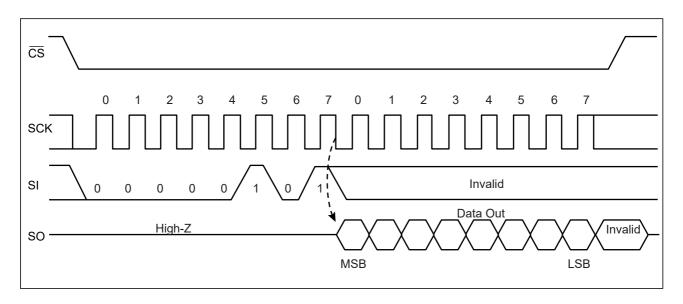
#### • WRDI

The WRDI command resets WEL (Write Enable Latch). Writing operation (WRITE command, WRSR command and WDIO command) are not performed when WEL is reset.



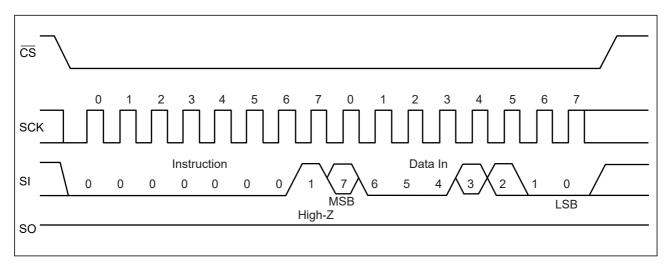
#### • RDSR

The RDSR command reads status register data. After op-code of RDSR is input to SI, 8-cycle clock is input to SCK. The SI value is invalid during this time. SO is output synchronously to a falling edge of SCK. In the RDSR command, repeated reading of status register is enabled by sending SCK continuously before rising of  $\overline{\text{CS}}$ .



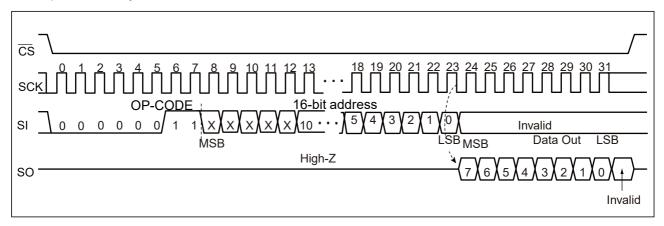
#### • WRSR

The WRSR command writes data to the nonvolatile memory bit of status register. After performing WRSR op-code to a SI pin, 8 bits writing data is input. WEL (Write Enable Latch) is not able to be written with WRSR command. A SI value corresponding to bit 1 is ignored. Bit 0 of the status register is fixed to "0" and cannot be written. The SI value corresponding to bit 0 is ignored. The WP signal level shall be fixed before performing the WRSR command, and not be changed until the end of command sequence.



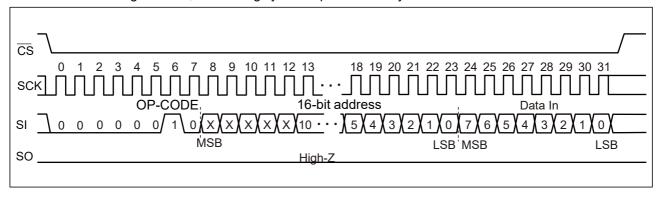
#### • READ

The READ command reads FeRAM memory cell array data. READ op-code and arbitrary 16 bits address are input to SI. The 5-bit upper address bits are ignored. Then, 8 clock cycles are input to SCK.  $\underline{SO}$  outputs 8-bit data synchronously to the falling edge of SCK. While reading, the SI value is invalid. When  $\overline{CS}$  is risen, the READ command is completed, otherwise it keeps on reading with automatic address increment which is enabled by continuously sending clocks to SCK in unit of 8 cycles before  $\overline{CS}$  rising. When it reaches the most significant address, it rolls over to the starting address, and reading cycle keeps on infinitely.



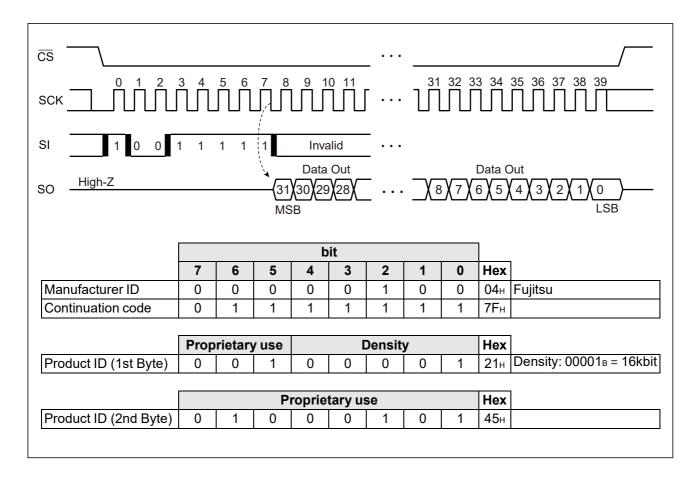
#### • WRITE

The WRITE command writes data to FeRAM memory cell array. WRITE op-code, arbitrary 16 bits of address and 8 bits of writing data are input to SI. The 5-bit upper address bit is ignored. When 8 bits of writing data is input, data is written to FeRAM memory cell array. Risen CS will terminate the WRITE command. However, if you continue sending the writing data for 8 bits each before CS rising, it is possible to continue writing with automatic address increment. When it reaches the most significant address, it rolls over to the starting address, and writing cycle keeps on infinitely.



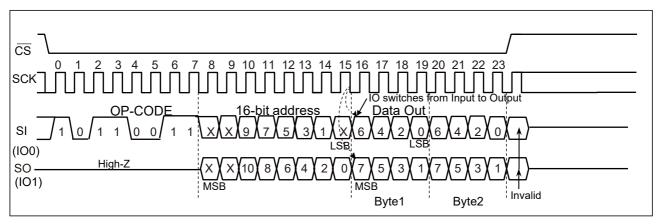
#### RDID

The RDID command reads fixed Device ID. After performing RDID op-code to SI, 32 clock cycles are input to SCK. The SI value is invalid during this time. SO is output synchronously to a falling edge of SCK. The output order is Manufacturer ID (8bit)/Continuation code (8bit)/Product ID (1st Byte)/Product ID (2nd Byte). In the RDID command, SO holds the output state of the last bit in 32-bit Device ID until  $\overline{CS}$  is risen.



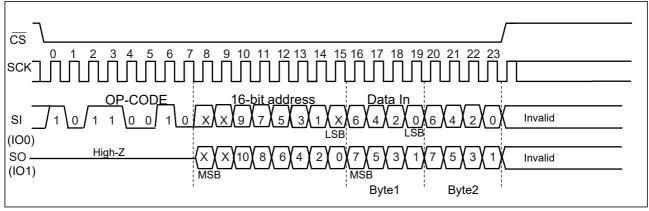
#### RDIO

The RDIO command reads FeRAM memory cell array data. RDIO op-code is input to SI(IO0). The 6 even address bits (A10, A8, A6, A4, A2, A0) of arbitrary 16 bits address are input to SO(IO1) and the 5 odd address bits (A9, A7, A5, A3, A1) are input to SI(IO0). The other address bits are ignored. Then, 4 clock cycles are input to SCK. SO(IO1) outputs 4 odd data bits (D7, D5, D3, D1) synchronously to the falling edge of SCK and SI(IO0) outputs 4 even data bits (D6, D4, D2, D0) as well. When  $\overline{\text{CS}}$  is risen, the RDIO command is completed, otherwise it keeps on reading with automatic address increment which is enabled by continuously sending clocks to SCK in unit of 4 cycles before  $\overline{\text{CS}}$  rising. When it reaches the most significant address, it rolls over to the starting address, and reading cycle keeps on infinitely.



#### • WDIO

The WDIO command writes data to FeRAM memory cell array. WDIO op-code is input to SI(IO0). The 6 even address bits (A10, A8, A6, A4, A2, A0) of arbitrary 16 bits address are input to SO(IO1) and the 5 odd address bits (A9, A7, A5, A3, A1) are input to SI(IO0). The other address bits are ignored. When the 4 odd writing data bits (D7, D5, D3, D1) are input to SO(IO1) and the 4 even writing data bits (D6, D4, D2, D0) are input to SI(IO0), they are written to FeRAM memory cell array. Risen  $\overline{\text{CS}}$  will terminate the WDIO command. However, if you continue sending the writing data for 8 bits each before  $\overline{\text{CS}}$  rising, it is possible to continue writing with automatic address increment. When it reaches the most significant address, it rolls over to the starting address, and writing cycle keeps on infinitely.



#### **■ BLOCK PROTECT**

Writing protect block for WRITE and WDIO commands are configured by the value of BP0 and BP1 in the status register.

BP1	BP0	Protected Block
0	0	None
0	1	600н to 7FFн (upper 1/4)
1	0	400н to 7FFн (upper 1/2)
1	1	000н to 7FFн (all)

#### **■ WRITING PROTECT**

Writing operation of WRITE, WDIO and WRSR commands are protected with the value of WEL, WPEN,  $\overline{\text{WP}}$  as shown in the table.

WEL	WPEN	WP	Protected Blocks	Unprotected Blocks	Status Register
0	Х	X	Protected	Protected	Protected
1	0	Х	Protected	Unprotected	Unprotected
1	1	0	Protected	Unprotected	Protected
1	1	1	Protected	Unprotected	Unprotected

#### ■ ABSOLUTE MAXIMUM RATINGS

Doromotor	Symbol	Rat	l lnit	
Parameter	Symbol	Min	Max	Unit
Power supply voltage*	$V_{\text{DD}}$	- 0.5	+ 2.5	V
Input voltage*	VIN	- 0.5	V <sub>DD</sub> + 0.5	٧
Output voltage*	Vouт	- 0.5	V <sub>DD</sub> + 0.5	V
Operation ambient temperature	TA	- 40	+ 125	°C
Storage temperature	Tstg	- 55	+ 125	°C

<sup>\*:</sup> These parameters are based on the condition that Vss is 0 V.

WARNING: Semiconductor devices may be permanently damaged by application of stress (including, without limitation, voltage, current or temperature) in excess of absolute maximum ratings. Do not exceed any of these ratings.

#### ■ RECOMMENDED OPERATING CONDITIONS

Parameter	Cumbal		l loit			
Parameter	Symbol	Min	Тур	Max	Unit	
Power supply voltage*1	$V_{DD}$	1.65	1.8	1.95	V	
Operation ambient temperature*2	TA	- 40	_	+ 125	°C	

<sup>\*1:</sup> These parameters are based on the condition that Vss is 0 V.

WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated under these conditions.

> Operation under any conditions other than these conditions may adversely affect reliability of device and could result in device failure.

No warranty is made with respect to any use, operating conditions or combinations not represented on this data sheet. If you are considering application under any conditions other than listed herein, please contact sales representatives beforehand.

<sup>\*2:</sup> Ambient temperature when only this device is working. Please consider it to be the almost same as the package surface temperature.

### ■ ELECTRICAL CHARACTERISTICS

#### 1. DC Characteristics

(within recommended operating conditions)

Parameter	Symbol	Condition		Value		Unit
Farameter	Symbol	Condition	Min	Тур	Max	Ullit
		CS = V <sub>DD</sub>		_	1	
Input leakage current	lu	WP, SCK, SI = 0 V to V <sub>DD</sub>	_	_	1	μΑ
Output leakage current	<b>I</b> LO	SO = 0 V to V <sub>DD</sub>			1	μΑ
Operating power supply current	I <sub>DD</sub>	SCK = 15 MHz	_	_	0.7	mA
Standby current	I <sub>SB</sub>	$SCK = SI = \overline{CS} = V_{DD}$		1 (25°C)	11 (125℃) 6 (85℃)	μΑ
Input high voltage	V <sub>IH</sub>	V <sub>DD</sub> = 1.65 to 1.95 V	$V_{DD} \times 0.8$	_	V <sub>DD</sub> + 0.3	V
Input low voltage	V <sub>IL</sub>	V <sub>DD</sub> = 1.65 to 1.95 V	- 0.5		$V_{\text{DD}} \times 0.2$	V
Output high voltage	Vон	$I_{OH} = -2 \text{ mA}$	V <sub>DD</sub> - 0.5		V <sub>DD</sub>	V
Output low voltage	Vol	I <sub>OL</sub> = 2 mA	Vss		0.4	٧

#### 2. AC Characteristics

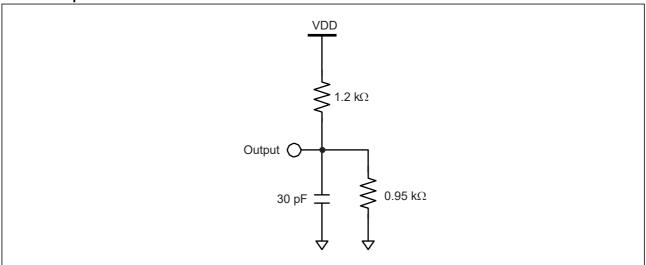
B	O mark at	Va	alue	11:4
Parameter	Symbol	Min	Max	Unit
SCK clock frequency for SPI	fск	_	15	MHz
Clock high time for SPI	tсн	26	_	ns
Clock low time for SPI	tc∟	26	_	ns
SCK clock frequency for Dual SPI	fск	_	7.5	MHz
Clock high time for Dual SPI	tсн	52	_	ns
Clock low time for Dual SPI	tcL	52	_	ns
Chip select set up time	tcsu	10	_	ns
Chip select hold time	tсsн	10	_	ns
Output disable time	top	_	20	ns
Output data valid time	todv	_	18	ns
Output hold time	tон	0	_	ns
Deselect time	t₀	30	_	ns
Data rising time	t <sub>R</sub>	_	50	ns
Data falling time	t⊧		50	ns
Data set up time	tsu	5		ns
Data hold time	tн	5	_	ns

#### **AC Test Condition**

Power supply voltage : 1.65 V to 1.95 V
Operation ambient temperature : -40 °C to + 125 °C
Input voltage magnitude : 0.3 V to 1.65 V

Input voltage magnitude : 0.3 V to 1.65 V
Input rising time : 5 ns
Input falling time : 5 ns
Input judge level : VDD/2
Output judge level : VDD/2

#### **AC Load Equivalent Circuit**

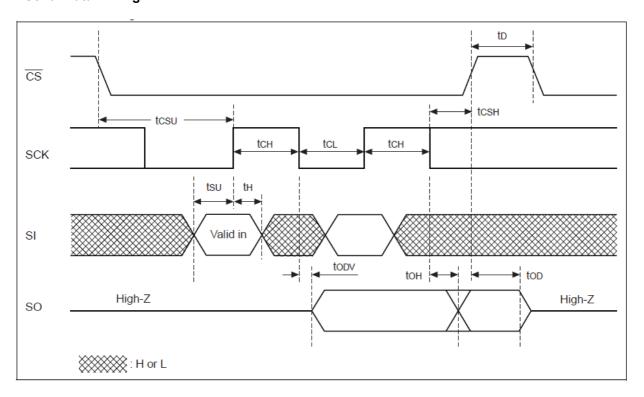


#### 3. Pin Capacitance

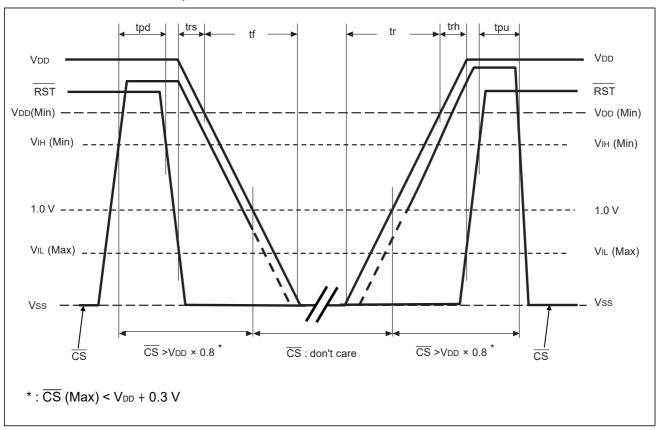
Domenator	Comple el	Conditions	Va	lue	l l m i t
Parameter	Symbol	Conditions	Min	Max	Unit
Output capacitance	Со	V <sub>DD</sub> =1.8V,	_	4	pF
Input capacitance	Cı	$V_{IN} = V_{OUT} = 0 \text{ V to } V_{DD},$ $f = 1 \text{ MHz}, T_A = +25 ^{\circ}\text{C}$		4	pF

#### **■ TIMING DIAGRAM**

#### • Serial Data Timing



#### **■ POWER ON/OFF SEQUENCE**



Doromotor	Cumbal	Va		
Parameter	Symbol	Min	Max	Unit
CS and RST level hold time at power OFF	tpd	400	_	ns
RST high to first access start	tpu	1	_	μs
Power supply falling time	tf	3	_	μs
Power supply rising time	tr	3	_	μs
RST setup time to VDD(min) at power OFF	trs	0		μs
RST hold time after VDD(min) at power ON	trh	1		μs

If the device does not operate within the specified conditions of read cycle, write cycle or power on/off sequence, memory data can not be guaranteed.

#### **■ Feram Characteristics**

Item	Min	Max	Unit	Parameter
Read/Write Endurance*1	10 <sup>13</sup>		Times/byte	Operation Ambient Temperature T <sub>A</sub> = + 125 °C
Data Retention*2	27.3		Years	Operation Ambient Temperature T <sub>A</sub> = + 105 °C
	8.4		Years	Operation Ambient Temperature T <sub>A</sub> = + 125 °C

<sup>\*1:</sup> Total number of reading and writing defines the minimum value of endurance, as an FeRAM memory operates with destructive readout mechanism.

#### ■ NOTE ON USE

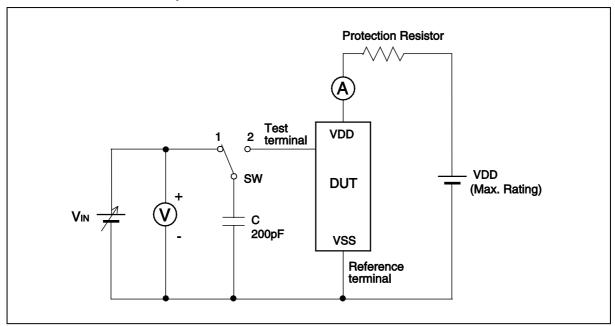
We recommend programming of the device after reflow. Data written before reflow cannot be guaranteed.

<sup>\*2 :</sup> Minimum values define retention time of the first reading/writing data right after shipment, and these values are calculated by qualification results.

#### **■ ESD AND LATCH-UP**

Test	DUT	Value
ESD HBM (Human Body Model)		≥  2000 V
JESD22-A114 compliant		' '
ESD CDM (Charged Device Model)	MB85RD16LXPN-G-AMEWE1	
JESD22-C101 compliant	INDOSTED TOEKT IN-O-AMEVIET	_
Latch-Up (C-V Method)		≥  200 V
Proprietary method		≥  200 V

#### C-V method of Latch-Up Resistance Test



Note: Charge voltage alternately switching 1 and 2 approximately 2 sec intervals. This switching process is considered as one cycle.

Repeat this process 5 times. However, if the latch-up condition occurs before completing 5times, this test must be stopped immediately.

#### ■ REFLOW CONDITIONS AND FLOOR LIFE

[ JEDEC MSL ] : Moisture Sensitivity Level 3 (IPC/JEDEC J-STD-020E)

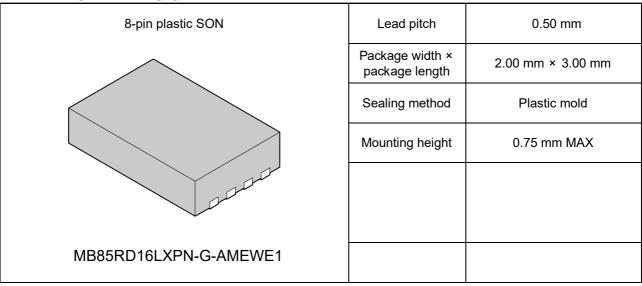
#### **■ CURRENT STATUS ON CONTAINED RESTRICTED SUBSTANCES**

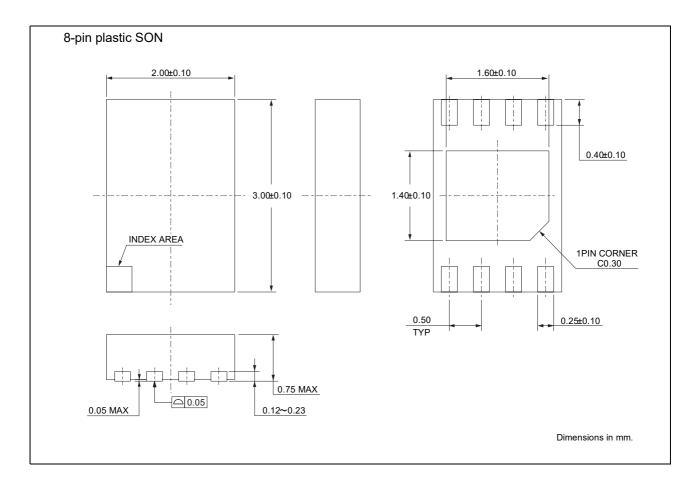
This product complies with the regulations of REACH Regulations, EU RoHS Directive and China RoHS.

### ■ ORDERING INFORMATION

Part number	Package	Shipping form	Minimum shipping quantity
MB85RD16LXPN-G-AMEWE1	8-pin, plastic SON	Embossed Carrier tape	1500

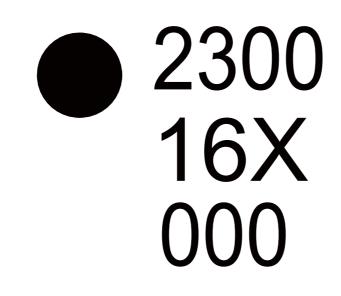
### **■ PACKAGE DIMENSION**





#### **■ MARKING**

[MB85RD16LXPN-G-AMEWE1]



[8-pin plastic SON]

2300: Year and Week code 16X: Product Name 000: Reference number

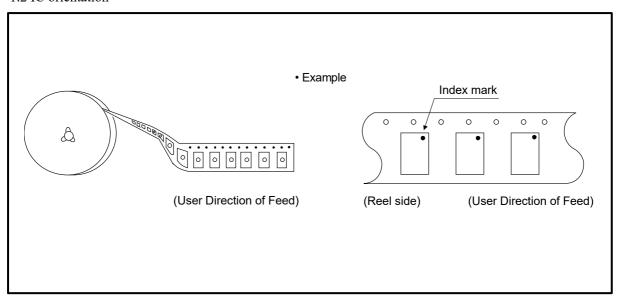
#### ■ PACKING

1. Emboss Tape

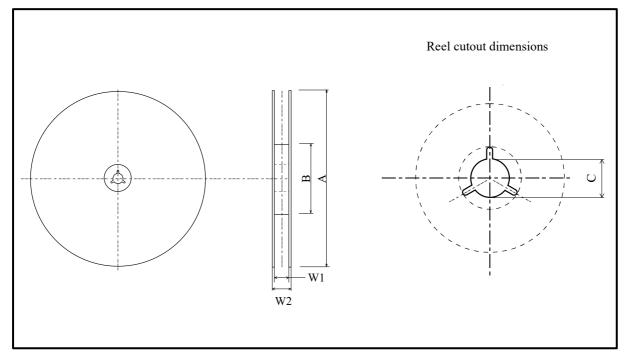
1.1 Tane Dimensions (not drawn to scale) (8-nin plastic SON)

1.1 Tape Dimensions (no	t drawn to scale) (8-pin p		
	Maximum storage cap		
ICs/reel ( φ 254mm)	ICs/inner box	ICs/outer box	
1500	1500	9000	
	(1 pack/inner box)	(6 inner boxes/outer box: Max)	_
	4.00  4.00  A  B  A  B  A  SECA-A  f temperature: No he should not be baked in the	(Dimensions in reat resistance.	0.20 0.90 SECB-B

#### 1.2 IC orientation



#### 1.3 Reel dimensions

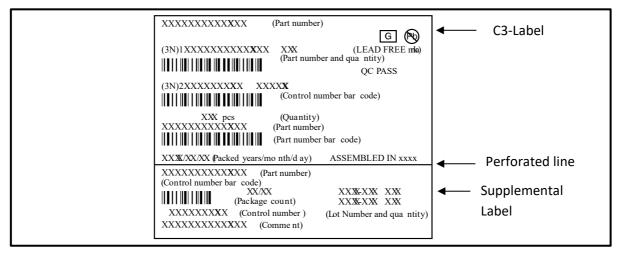


#### Dimensions in mm

Tape width	Α	В	С	W1	W2
8	254	100	13	9.5	13.5

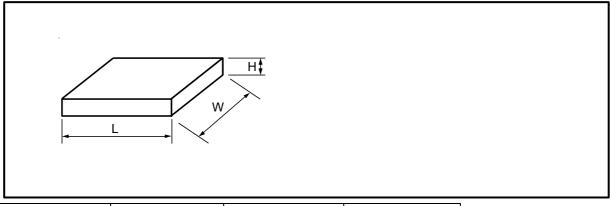
#### 1.4 Products label indicators

Label I: Label on Inner box/Moisture Barrier Bag/ (It sticks it on the reel for the emboss taping) [C-3 Label (50mm x 100mm) Supplemental Label (20mm x 100mm)]



#### 1.5 Dimensions for container

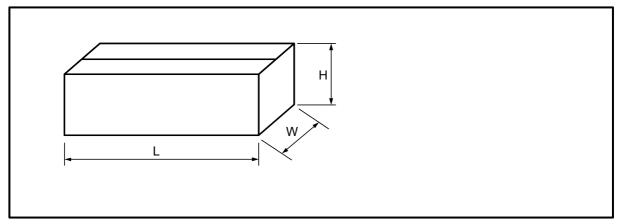
#### (1) Dimensions for inner box



Tape width	L	W	Н
8	265	260	50

(Dimensions in mm)

#### (2) Dimensions for outer box



L	W	Н
565	270	180

(Dimensions in mm)

### ■ MAJOR CHANGES IN THIS EDITION

A change on a page is indicated by a vertical line drawn on the left side of that page.

Page	Section	Change Results
22	■ PACKAGE DIMENSION	Partly revised.

#### RAMXEED LIMITED

Shin-Yokohama Chuo Building, 2-100-45 Shin-Yokohama, Kohoku-ku, Yokohama, Kanagawa 222-0033, Japan https://ramxeed.com/

#### All Rights Reserved.

RAMXEED LIMITED, its subsidiaries and affiliates (collectively, "RAMXEED") reserves the right to make changes to the information contained in this document without notice. Please contact your RAMXEED sales representatives before order of RAMXEED device.

Information contained in this document, such as descriptions of function and application circuit examples is presented solely for reference to examples of operations and uses of RAMXEED device. RAMXEED disclaims any and all warranties of any kind, whether express or implied, related to such information, including, without limitation, quality, accuracy, performance, proper operation of the device or non-infringement. If you develop equipment or product incorporating the RAMXEED device based on such information, you must assume any responsibility or liability arising out of or in connection with such information or any use thereof. RAMXEED assumes no responsibility or liability for any damages whatsoever arising out of or in connection with such information or any use thereof.

Nothing contained in this document shall be construed as granting or conferring any right under any patents, copyrights, or any other intellectual property rights of RAMXEED or any third party by license or otherwise, express or implied. RAMXEED assumes no responsibility or liability for any infringement of any intellectual property rights or other rights of third parties resulting from or in connection with the information contained herein or use thereof.

The products described in this document are designed, developed and manufactured as contemplated for general use including without limitation, ordinary industrial use, general office use, personal use, and household use, but are not designed, developed and manufactured as contemplated (1) for use accompanying fatal risks or dangers that, unless extremely high levels of safety is secured, could lead directly to death, personal injury, severe physical damage or other loss (including, without limitation, use in nuclear facility, aircraft flight control system, air traffic control system, mass transport control system, medical life support system and military application), or (2) for use requiring extremely high level of reliability (including, without limitation, submersible repeater and artificial satellite). RAMXEED shall not be liable for you and/or any third party for any claims or damages arising out of or in connection with above-mentioned uses of the products.

Any semiconductor devices fail or malfunction with some probability. You are responsible for providing adequate designs and safeguards against injury, damage or loss from such failures or malfunctions, by incorporating safety design measures into your facility, equipments and products such as redundancy, fire protection, and prevention of overcurrent levels and other abnormal operating conditions.

The products and technical information described in this document are subject to the Foreign Exchange and Foreign Trade

The products and technical information described in this document are subject to the Foreign Exchange and Foreign Trade Control Law of Japan, and may be subject to export or import laws or regulations in U.S. or other countries. You are responsible for ensuring compliance with such laws and regulations relating to export or re-export of the products and technical information described herein.

All company names, brand names and trademarks herein are property of their respective owners.